EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	1743	(702/150,109,110,111,112,113,116).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/03/11 13:59
L2	793	(702/142,143,144,145,146,147).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/03/11 13:59
L3	1002	(702/151,152,153,163).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/03/11 13:59
L4	938	(73/865.9).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/03/11 13:59
L5	2340	(324/207.2,207.25).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/03/11 14:00
L6	529	(324/76.12,76.14).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/03/11 14:00
L7	930	(324/207.12,207.14,76.13).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/03/11 14:04
L8	454	(702/94).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/03/11 14:04
L9	4949	(squar$3 with root$1) with (sum near squar$3)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:05
L10	30	((squar$3 with signal$1) same (quadrature with component$1) same (compensat$3 and filter$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:06
L11	8	(determin$3 with (position$3 near rotor$1) with motor$1) and ((amplitud$3 magnitud$3) with correct $3) and (quadratur$3 with signal$1)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:08
L12	1	((motor$1 with rotor$1) with (position$1)) and (weigh$3 same (invers$3 with (cosin$3 and sin $3))) and (sum$3 with output$3) and (sens$3 with position$3) and ((amplitud$3 magnitud$3) with (correctS3 compensat$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:10

L13	0	((motor$3 with rotor$1 with position$3) same (determin$3 calculat$3 manipulat$3 obtain$3 monitor$3)) and (weighS3 with factor$1) and ((sine$1 with cosine$1) with (invers$3 and component $1)) and (zero with crossing$1) and ((amplitud$3 magnitud$3) with (correct$3 filter$3 window$3 compensat$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:11
L14	1	(((motor$3 with rotor$1 with position$3) same (determin$3 calculat$3 manipulat$3 obtain$3 monitor$3)) and (weigh$3 with factor$1) and ((sine$1 with cosine$1) with (invers$3 and component $1)) and (zero with crossing$1) and ((amplitud$3 magnitud$3) with (correct$3 filter$3 window$3 compensat$3)))".clm.."	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:12
L15	2	9 and 11	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:13
L16	1	15 and 12	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:13
L17	0	16 and (1 2 3 4 5 6 7 8)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:13
L18	0	14 and (1 2 3 4 5 6 7 8)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:13
L19	2	(determin$3 with rotor$3 with position$3) same ((quadrat$3 with signal$1) with (compensat$3 correct$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:14
L20	6	(determin$3 with rotor$3 with position$3) same ((quadrat$3 with signal$1) with (compensat$3 correct$3 filter$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:15
L21	1	(determin$3 with rotor$3 with position$3) same ((quadrat$3 with signal$1) with (compensat$3 correct$3 filter$3)) same (sum$3 with (squar$3 with root$3)) same (sin$3 and cos$3)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:15
L22	0	21 and (1 2 3 4 5 6 7 8)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:17
L23	3	divid$3 with (sin$3 cos$3) with ((correct$3 compensat$3) with (amplitude$1 and factor$1))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:17
L24	1	23 and 20	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:19
L25	6	(("5746005") or ("5610683") or ("4634949") or ("5808462") or ("5677686") or ("5663643")).PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/03/11 14:20

L26	0	25 and 12	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:20
L27	151	("2775755" I "2944157" I "3096444" I "3870871" I "4131363" I "4303881" I "4318617" I "4449191" I "4480910" I "4509852" I "4634270" I "4675614" I "4676631" I "4719449" I "4720732" I "4742376" I "4890056" I "5032999" I "5121256" I "5155696" I "5216346" I "5239490" I "5301434" I "5453684" I "5463393" I "5576618" I "5714877" I "5731698"). PN. OR ("4634949" I "5610683" I "5663643" I "5677686" I "5746005" I "5808462").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:23
L28	2	(rotor$3 with position$3) and (((amplitude$1 with magnitude$1) with (correct$3 compensat$3 filter $3)) with divider$1)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:42
L29	5065	((squar$3 with root$1) with (sum$3 near squar$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 14:43
L30	120	(341/8,115).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/03/11 16:48
L31	8	(determin$3 with (position$3 near rotor$1) with motor$1) and ((amplitud$3 magnitud$3) with correct $3) and (quadratur$3 with signal$1)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 16:48
L32	2	30 and 31	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 16:50
L33	0	32 and (1 2 3 4 5 6 7 8)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 16:50
L34	1	((motor$1 with rotor$1) with (position$3) and (invers $3 with (cosine$1 and sine$1)) and ((magnitude amplitude$1) with (compensat$3 offset$3 correct$3 filter$3)) and (weigh$3 with factor$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 16:51
L35	1	((((squar$3 with root$1) with (sum near squar$3)) and (divid$3 with (compensat$3 near amplitude $1))) and ((cosine$1 and sine$1) with invers$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 16:52
L36	30	((squar$3 with signal$1) same (quadratur$3 with component$1) same (compensat$3 and filter$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 16:53
L37	1	(position$3 with determin$3) same (rotor$3 with rotat$3 with position$3) and ((squar$3 and root$3) with (cosin$3 and sine$1)) and ((amplitude$1 magnitude$1) with (correct$4 filter$3 compensat$4 offset$3)) and (weigh$3 with invers$3 with (cosine $1 and sine$1))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 16:55

L38	0	37 and (1 2 3 4 5 6 7 8 30)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:13
L39	1	((position$3 with determin$3) same (rotor$3 with rotat$3 with position$3) and ((squar$3 and root$3) with (cosin$3 and sine$1)) and ((amplitude$1 magnitude$1) with (correct$4 filter$3 compensat$4 offset$3)) and (weigh$3 with invers$3 with (cosine $1 and sine$1))).clm.	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:13
L40	0	39 and (1 2 3 4 5 6 7 8 30)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:13
L41	627	divid$3 same ((compensat$3 correct$3) near (amplitude$1 peak$1))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:14
L42	10	41 and (rss (squar$3 with root$1 with sin$3 and cosin$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:15
L43	1	(41 and (rss (squar$3 with root$1 with sin$3 and cosin$3))) and ((determin$3 with (position$3 near rotor$1) with motor$1) and (amplitud$3 with correct $3) and (quadratur$3 with signal$1))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:16
L44	0	43 and (1 2 3 4 5 6 7 8 30)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:17
L45	0	43 and 25	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:18
L46	1	25 and 42	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:18
L47	0	41 and (rss (squar$3 with root$1 with sin$3 and cosin$3)) and ((invers$3 with (cosin$3 and sine$1)) with weigh$3) and (zero with cross$3)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:19
L48	0	46 and 47	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:21
L49	6	(position$3 with (measur$3 determin$3)) and (roto $3 with motor$1) and (sens$3 with rotat$3 with (quadratur$3 near signal$1))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:24
L50	0	(position$3 with (measur$3 determin$3)) and (roto $3 with motor$1) and (sens$3 with rotat$3 with (quadratur$3 near signal$1)) and 25	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:27
L51	0	(position$3 with (measur$3 determin$3)) and (roto $3 with motor$1) and (sens$3 with rotat$3 with (quadratur$3 near signal$1)) and (1 2 3 4 5 6 7 8 30)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:27

L52	1	(position$3 with (measur$3 determin$3)) and (roto $3 with motor$1) and (sens$3 with rotat$3 with (quadratur$3 near signal$1)) and ((invers$3 and squar$3 and root$3) with (sin$3 cosin$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:28
L53	0	52 and (1 2 3 4 5 6 7 8 30)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 17:29
L54	1	(position$3 with (measur$3 determin$3)) and (roto $3 with motor$1) and (sens$3 with rotat$3 with (quadratur$3 near signal$1)) and (weigh$3 with (invers$3 with (sin$3 and cosin$3)))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 18:14
L55	1	((position$3 with (measur$3 determin$3)) and (roto $3 with motor$1) and (sens$3 with rotat$3 with (quadratur$3 near signal$1)) and (weigh$3 with (invers$3 with (sin$3 and cosin$3)))).clm.	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 18:20
L56	1	((rotor$1 with position$3) with (determin$3 identif$3 examin$3 analy$3)) and ((amplitude$1 magnitudeS1) with (correct$3 compensat$3 remedy $3)) and ((sum$3 total) with (cosine$1 and sine$1)) and ((invers$3 with function$3) with (cosine$1 and sine$1)) and ((squar$3 rootS3 radial$3) with (sine and cosin$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 18:21
L57	0	(((rotor$1 with position$3) with (determin$3 identif $3 examin$3 analy$3)) and ((amplitude$1 magnitudeS1) with (correct$3 compensat$3 remedy $3)) and ((sum$3 total) with (cosine$1 and sine$1)) and ((invers$3 with function$3) with (cosine$1 and sine$1)) and ((squar$3 rootS3 radial$3) with (sine and cosin$3))).clm.	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 18:21
L58	0	57 and (1 2 3 4 5 6 7 30)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 18:22
L59	0	56 and (1 2 3 4 5 6 7 25 30)	US-PGPUB; USPAT; USOCR	OR	ON	2008/03/11 18:22

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